

# Modeling with SQUAD

Luis Mendoza

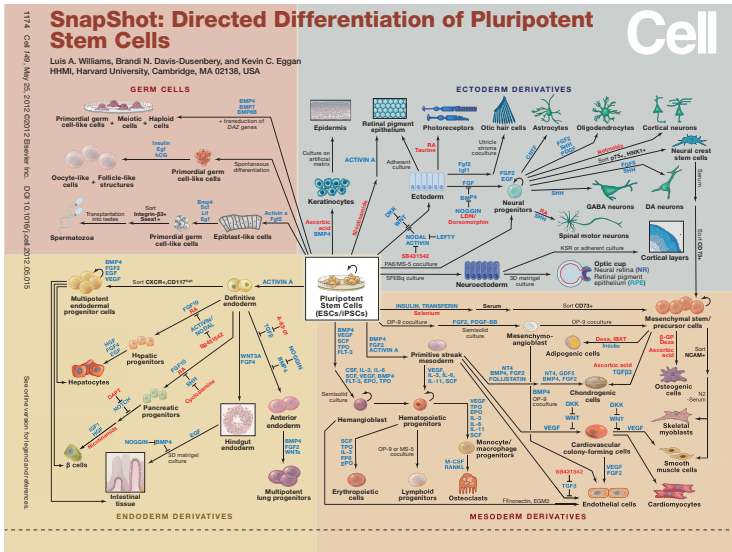
lmendoza@biomedicas.unam.mx

Instituto de Investigaciones Biomédicas  
Universidad Nacional Autónoma de México



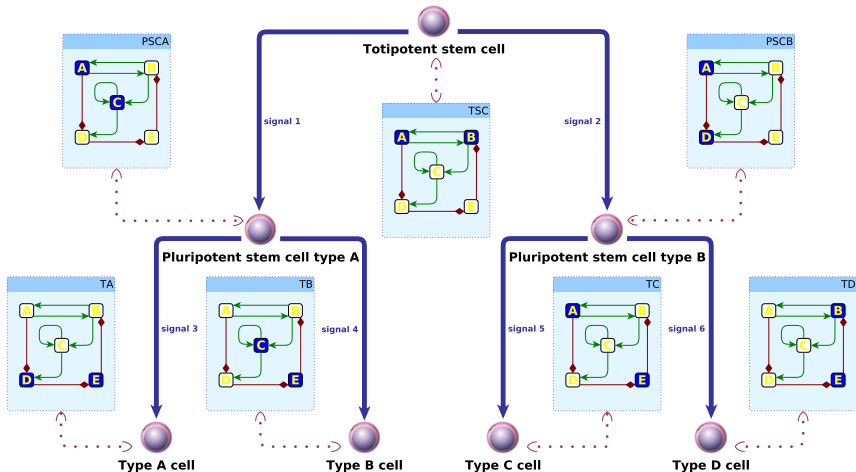
# Differentiation of human cells

Williams *et al.* (2012) *Cell* 149. DOI: 10.1016/j.cell.2012.05.015



# The big picture

Cell differentiation as transitions among attractors



# What is SQUAD?

- ▶ Stands for *S*tandardized *Q*ualitative *D*ynamical systems.
- ▶ Approximates a Boolean network with the use of a set of ordinary differential equations.
- ▶ Variables representing the state of activation are normalized: they are constrained in the range  $[0,1]$ .
- ▶ Enables a direct comparison of the attractors obtained with a continuous model against the attractors of a purely binary model.

# Why?

- ▶ There are many biological systems where there are gradients, and concentration-dependent effects.
- ▶ There is not enough quantitative data available for such systems.

## Theoretical Biology and Medical Modelling



Research

Open Access

### A method for the generation of standardized qualitative dynamical systems of regulatory networks

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This article is available from: <http://www.tbiomed.com/content/3/1/13>

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# Discrete equations

## Equation 1.

$$x_i(t+1) = \begin{cases} (x_1^a(t) \vee x_2^a(t) \dots \vee x_n^a(t)) \wedge \neg(x_1^i(t) \vee x_2^i(t) \dots \vee x_m^i(t)) & \$ \\ x_1^a(t) \vee x_2^a(t) \dots \vee x_n^a(t) & \$\$ \\ \neg(x_1^i(t) \vee x_2^i(t) \dots \vee x_m^i(t)) & \$\$\$ \end{cases}$$

$\vee, \wedge,$  and  $\neg$  are the logical operators OR, AND, and NOT

$$x_i \in \{0, 1\}$$

$\{x_n^a\}$  is the set of activators of  $x_i$

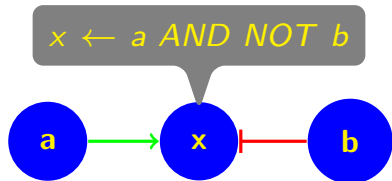
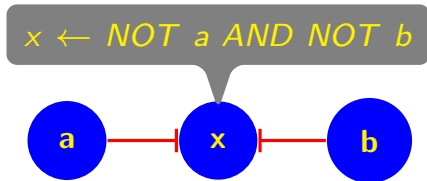
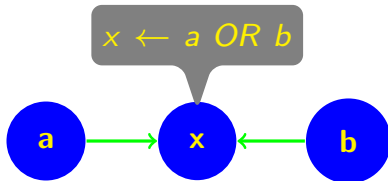
$\{x_m^i\}$  is the set of inhibitors of  $x_i$

$\$$  is used if  $x_i$  has activators and inhibitors

$\$\$$  is used if  $x_i$  has only activators

$\$\$\$$  is used if  $x_i$  has only inhibitors

# Discrete equations





## Finding attractors analyzing regulatory circuits

The logical formalism developed by [René Thomas](#) enables us to dissociate a complex network into a well-defined set of feedback circuits and check their dynamical roles individually, yet keeping complete control of the ways in which these circuits are interconnected.

# Continuous equations

## Equation 3.

$$\frac{dx_i}{dt} = \frac{-e^{0.5h} + e^{-h(\omega_i - 0.5)}}{(1 - e^{0.5h})(1 + e^{-h(\omega_i - 0.5)})} - \gamma_i x_i$$

$$\omega_i = \begin{cases} \left( \frac{1 + \sum \alpha_n}{\sum \alpha_n} \right) \left( \frac{\sum \alpha_n x_n^a}{1 + \sum \alpha_n x_n^a} \right) \left( 1 - \left( \frac{1 + \sum \beta_m}{\sum \beta_m} \right) \left( \frac{\sum \beta_m x_m^i}{1 + \sum \beta_m x_m^i} \right) \right) & \S \\ \left( \frac{1 + \sum \alpha_n}{\sum \alpha_n} \right) \left( \frac{\sum \alpha_n x_n^a}{1 + \sum \alpha_n x_n^a} \right) & \S\S \\ \left( 1 - \left( \frac{1 + \sum \beta_m}{\sum \beta_m} \right) \left( \frac{\sum \beta_m x_m^i}{1 + \sum \beta_m x_m^i} \right) \right) & \S\S\S \end{cases}$$

$$0 \leq x_i \leq 1$$

$$0 \leq \omega_i \leq 1$$

$$h, \alpha_n, \beta_m, \gamma_i > 0$$

$\{x_n^a\}$  is the set of activators of  $x_i$

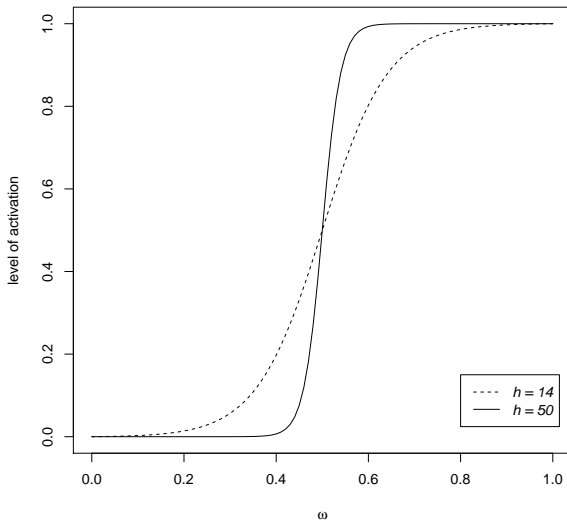
$\{x_n^i\}$  is the set of inhibitors of  $x_i$

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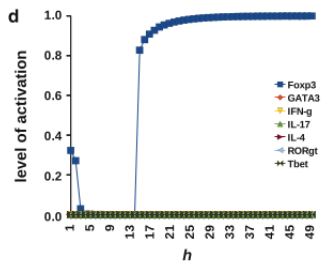
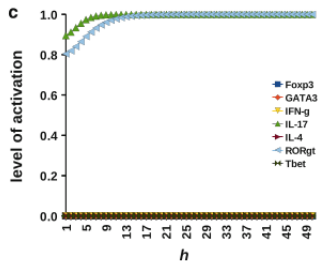
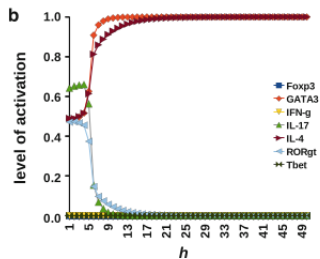
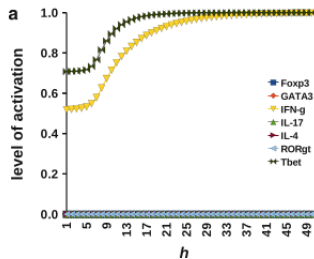
$\S\S\S$  is used if  $x_i$  has only inhibitors

# The parameter $h$



# Relative insensitivity to parameter $h$

Mendoza and Pardo (2010). *Theor. Biosci.* 129: 283



# Continuous equations

## Equation 3.

$$\frac{dx_i}{dt} = \frac{-e^{0.5h} + e^{-h(\omega_i - 0.5)}}{(1 - e^{0.5h})(1 + e^{-h(\omega_i - 0.5)})} - \gamma_i x_i$$

$$\omega_i = \begin{cases} \left( \frac{1 + \sum \alpha_n}{\sum \alpha_n} \right) \left( \frac{\sum \alpha_n x_n^a}{1 + \sum \alpha_n x_n^a} \right) \left( 1 - \left( \frac{1 + \sum \beta_m}{\sum \beta_m} \right) \left( \frac{\sum \beta_m x_m^i}{1 + \sum \beta_m x_m^i} \right) \right) & \S \\ \left( \frac{1 + \sum \alpha_n}{\sum \alpha_n} \right) \left( \frac{\sum \alpha_n x_n^a}{1 + \sum \alpha_n x_n^a} \right) & \S\S \\ \left( 1 - \left( \frac{1 + \sum \beta_m}{\sum \beta_m} \right) \left( \frac{\sum \beta_m x_m^i}{1 + \sum \beta_m x_m^i} \right) \right) & \S\S\S \end{cases}$$

$$0 \leq x_i \leq 1$$

$$0 \leq \omega_i \leq 1$$

$$h, \alpha_n, \beta_m, \gamma_i > 0$$

$\{x_n^a\}$  is the set of activators of  $x_i$

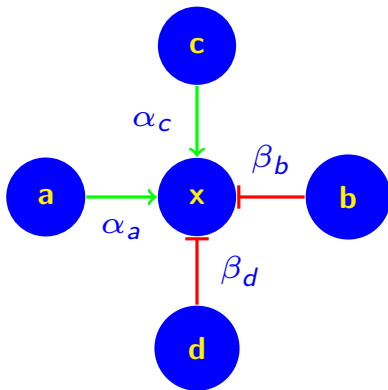
$\{x_n^i\}$  is the set of inhibitors of  $x_i$

$\S$  is used if  $x_i$  has activators and inhibitors

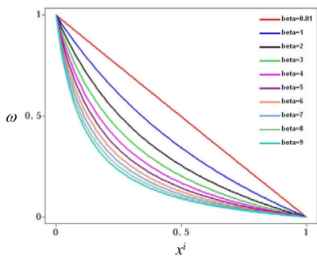
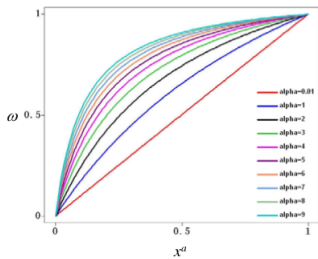
$\S\S$  is used if  $x_i$  has only activators

$\S\S\S$  is used if  $x_i$  has only inhibitors

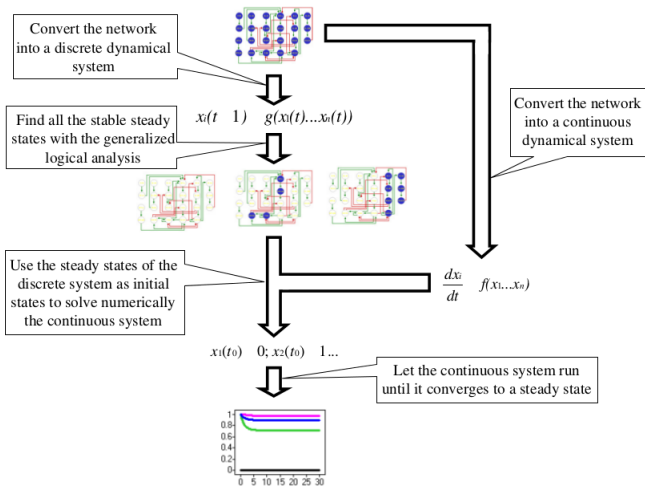
# Parameters $\alpha$ and $\beta$



# Strength of interactions



# SQUAD workflow





## BMC Bioinformatics



Software

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### Dynamic simulation of regulatory networks using SQUAD

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Ioannis Xenarios<sup>\*3</sup> and Luis Mendoza<sup>\*4</sup>

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\* Corresponding authors

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*BMC Bioinformatics* 2007, **8**:462 doi:10.1186/1471-2105-8-462

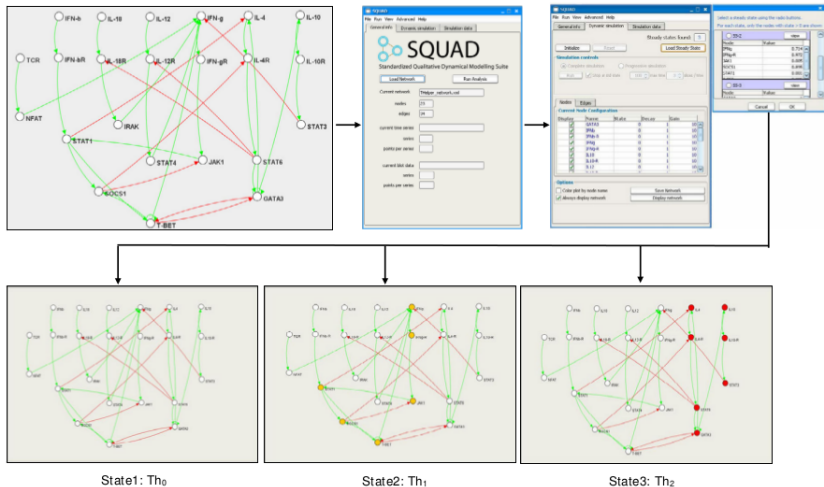
Accepted: 26 November 2007

This article is available from: <http://www.biomedcentral.com/1471-2105/8/462>

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# Workflow



# Finding the steady states of a network with BDDs



Fig. 2. An example of Gene Regulatory Network

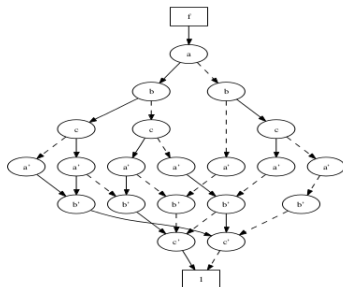
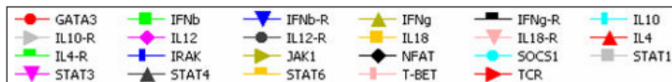
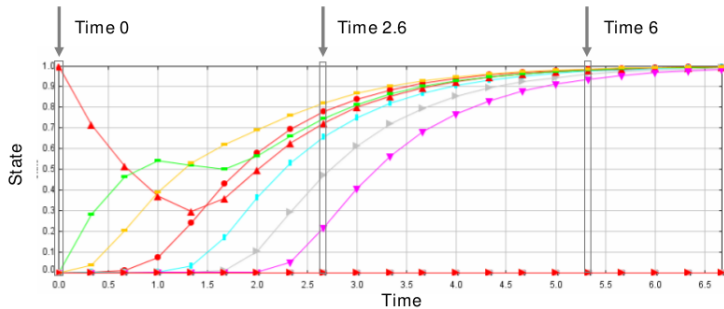


Fig. 3. BDD representing the state space of example in figure 2. The dashed edges represent 0 evaluation of the variables and the solid edges represent the 1 evaluation. For clarity, edges going to 0-terminal are not shown in this figure.

# Dynamics



# Perturbations

A

The screenshot shows the 'fdt Perturbation Protocol' dialog box in 'Tree view' mode. The tree structure is as follows:

- perturbations
  - perturbation (id=**IL-4 Pulse**, initialState=TH0)
    - singlepulse (parameter=state, target=**IL-4**, time=3.5, value=1.0)
  - perturbation (id=**Perturbation of Th2 state**, initialState=TH0)
    - singlepulse (parameter=state, target=**IL-4**, time=3.5, value=1.0)
    - singlepulse (parameter=state, target=**IFN-g**, time=10.0, value=1.0)
- states
  - state (id=TH0)
    - activenode (id=GATA3, state=0.0)
    - activenode (id=IFN-b, state=0.0)
    - activenode (id=IFN-bR, state=0.0)
    - activenode (id=IFN-g, state=0.0)
    - activenode (id=IFN-gR, state=0.0)
    - activenode (id=IL-10, state=0.0)
    - activenode (id=IL-10R, state=0.0)
    - activenode (id=IL-12, state=0.0)
    - activenode (id=IL-12R, state=0.0)
    - activenode (id=IL-18, state=0.0)
    - activenode (id=IL-18R, state=0.0)
    - activenode (id=IL-4, state=0.0)

Buttons at the bottom: Delete, Edit, Add, Cancel, OK.

B



The screenshot shows the 'fdt Perturbation Protocol' dialog box in 'Text view' mode. The XML content is as follows:

```
<?xml version="1.0" encoding="UTF-8"?>
<protocol level="1.0">
  <perturbations>
    <perturbation id="IL-4 Pulse" initialState="TH0">
      <singlepulse parameter="state" target="IL-4" time="3.5" value="1.0" />
    </perturbation>
    <perturbation id="Perturbation of Th2 state" initialState="TH0">
      <singlepulse parameter="state" target="IL-4" time="3.5" value="1.0" />
      <singlepulse parameter="state" target="IFN-g" time="10.0" value="1.0" />
    </perturbation>
  </perturbations>
  <states>
    <state id="TH0">
      <activenode id="GATA3" state="0.0" />
      <activenode id="IFN-b" state="0.0" />
      <activenode id="IFN-bR" state="0.0" />
      <activenode id="IFN-g" state="0.0" />
      <activenode id="IFN-gR" state="0.0" />
      <activenode id="IL-10" state="0.0" />
      <activenode id="IL-10R" state="0.0" />
      <activenode id="IL-12" state="0.0" />
      <activenode id="IL-12R" state="0.0" />
      <activenode id="IL-18" state="0.0" />
      <activenode id="IL-18R" state="0.0" />
      <activenode id="IL-4" state="0.0" />
    </state>
  </states>
</protocol>
```

Buttons at the bottom: Cancel, OK.

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Peterson H, Abu Dawud R, Garg A, Wang Y, Vilo J, Xenarios I, Adjaye J

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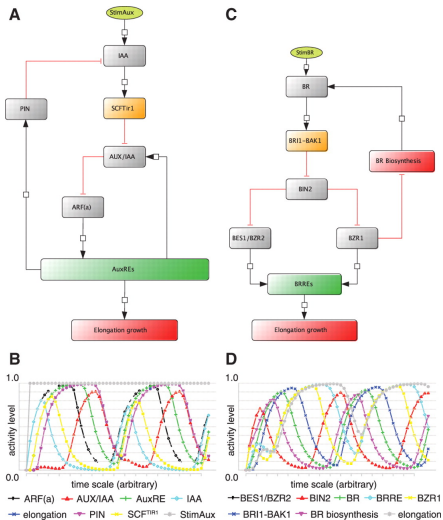
Martial Sankar<sup>1,\*</sup>, Karen S. Osmond<sup>1</sup>, Jakub Rolcik<sup>2</sup>, Bojan Gujas<sup>1</sup>, Danuse Tarkowska<sup>2</sup>, Miroslav Strnad<sup>2</sup>, Ioannis Xenarios<sup>3</sup> and Christian S. Hardtke<sup>1,\*</sup>

<sup>1</sup>Department of Plant Molecular Biology, University of Lausanne, CH-1015 Lausanne, Switzerland, <sup>2</sup>Laboratory of Growth Regulators, Palacky University and Institute of Experimental Botany Academy of Sciences of the Czech Republic, CZ-78371 Olomouc, Czech Republic and <sup>3</sup>Swiss Institute of Bioinformatics, CH-1015 Lausanne, Switzerland

Associate Editor: Alfonso Valencia

# SQUADD

Used to model cyclic behavior





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## SQUADD

### Add-on of the SQUAD Software

Bioconductor version: Release (2.13)

This package SQUADD is a SQUAD add-on. It permits to generate SQUAD simulation matrix, prediction Heat-Map and Correlation Circle from PCA analysis.

Author: Martial Sankar, supervised by Christian Hardtke and Ioannis Xenarios

Maintainer: Martial Sankar <[martial.sankar@unil.ch](mailto:martial.sankar@unil.ch)>

To install this package, start R and enter:

```
source("http://bioconductor.org/biocLite.R")
biocLite("SQUADD")
```

To cite this package in a publication, start R and enter:

```
citation("SQUADD")
```

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# Modification of SQUAD

Sánchez-Corrales *et al.* (2010). *J. Theor. Biol.* **264**: 971

Journal of Theoretical Biology 264 (2010) 971–983



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## The *Arabidopsis thaliana* flower organ specification gene regulatory network determines a robust differentiation process

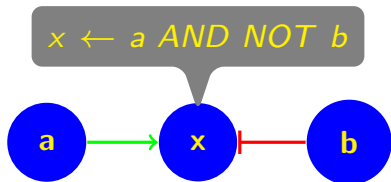
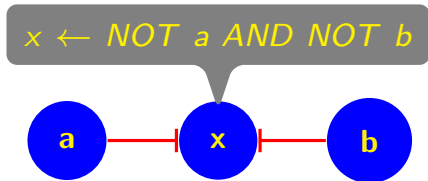
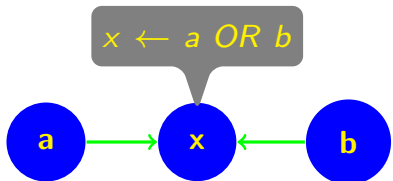
Yara-Elena Sánchez-Corrales<sup>a,1</sup>, Elena R. Álvarez-Buylla<sup>a,b</sup>, Luis Mendoza<sup>b,c,\*</sup>

<sup>a</sup> Instituto de Ecología, Universidad Nacional Autónoma de México, Ciudad Universitaria, D.F. CP04510, México

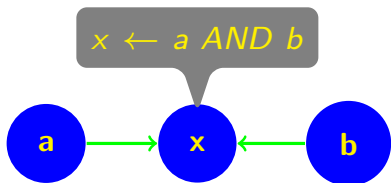
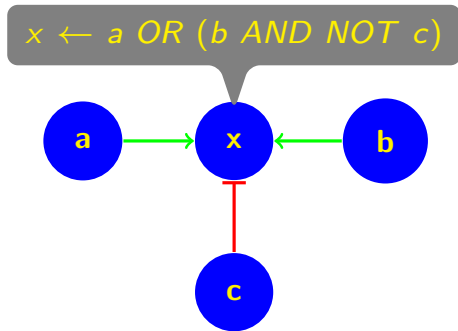
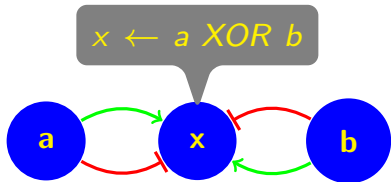
<sup>b</sup> Centro de Ciencias de la Complejidad, Universidad Nacional Autónoma de México, Ciudad Universitaria, D.F. CP04510, México

<sup>c</sup> Instituto de Investigaciones Biomédicas, Universidad Nacional Autónoma de México, Ciudad Universitaria, D.F. CP04510, México

# In the original version of SQUAD ...

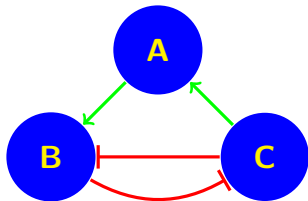


... this is not possible



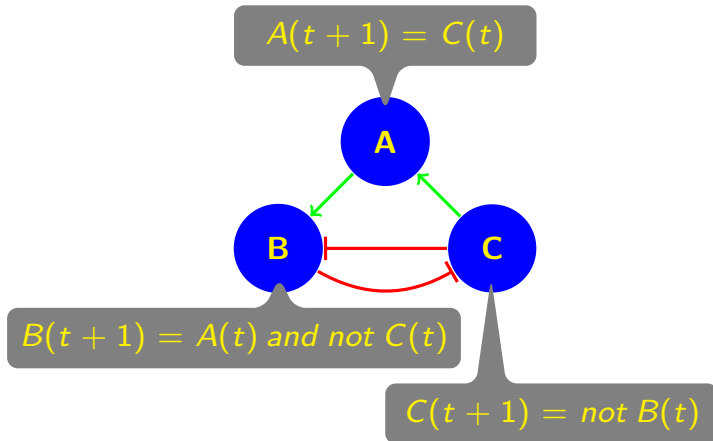
# A Boolean Network

Its topology



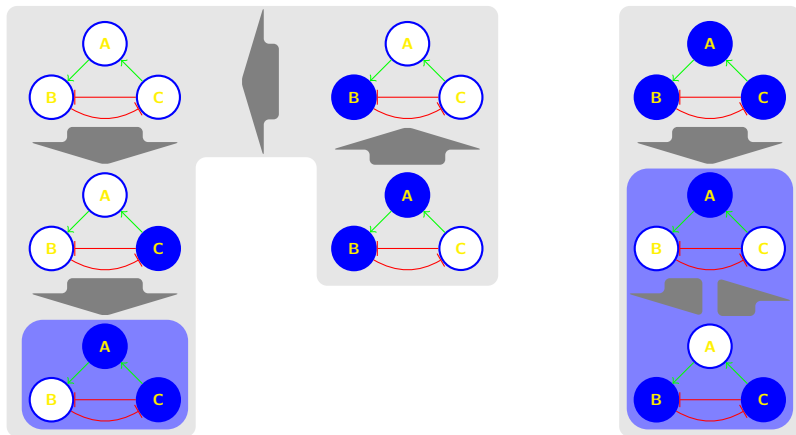
# A Boolean Network

Its associated functions



# A Boolean Network

Attractors and basins of attraction



# The continuous equations

$$\frac{dx_i}{dt} = \frac{-e^{0.5h_i} + e^{-h_i(\omega_i - 0.5)}}{(1 - e^{0.5h_i})(1 + e^{-h_i(\omega_i - 0.5)})} - \gamma_i x_i$$

$x_i$  is the activation level of node  $i$ .

$\omega_i$  is the continuous form of the logical rule describing the response of the node.

$h_i$  is the gain of the input.

$\gamma_i$  is the decay rate.



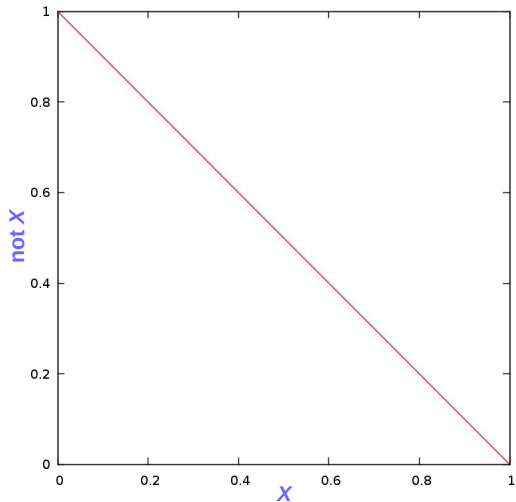
## From classic to fuzzy logic

$$\text{NOT } x \rightarrow 1 - x$$

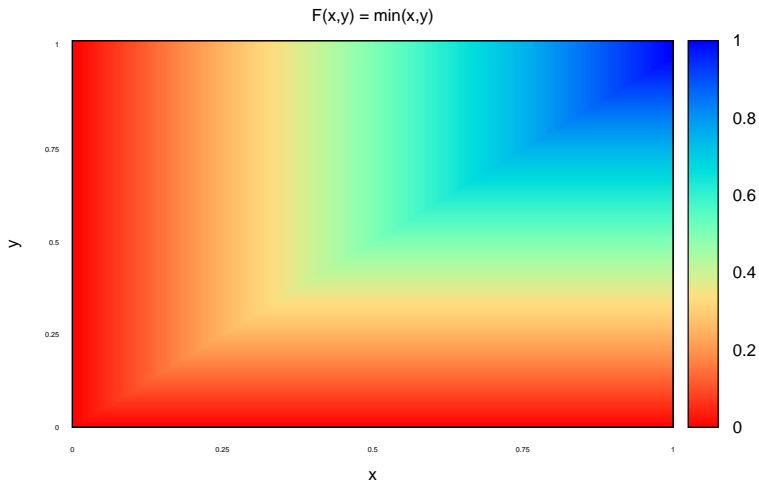
$$x \text{ AND } y \rightarrow \min(x, y)$$

$$x \text{ OR } y \rightarrow \max(x, y)$$

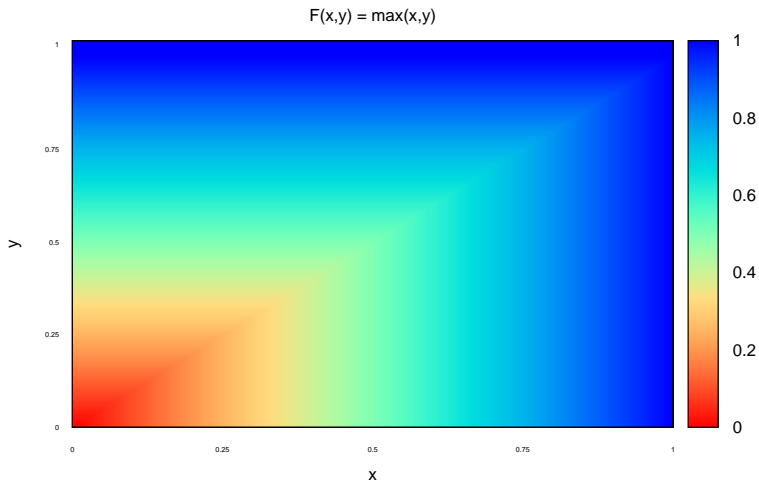
# The fuzzy logic version of the NOT function



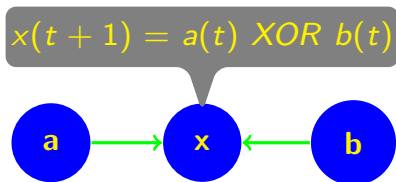
# The fuzzy logic version of the AND function



# The fuzzy logic version of the OR function



## From a discrete to a continuous function



$$x \leftarrow a \text{ XOR } b$$

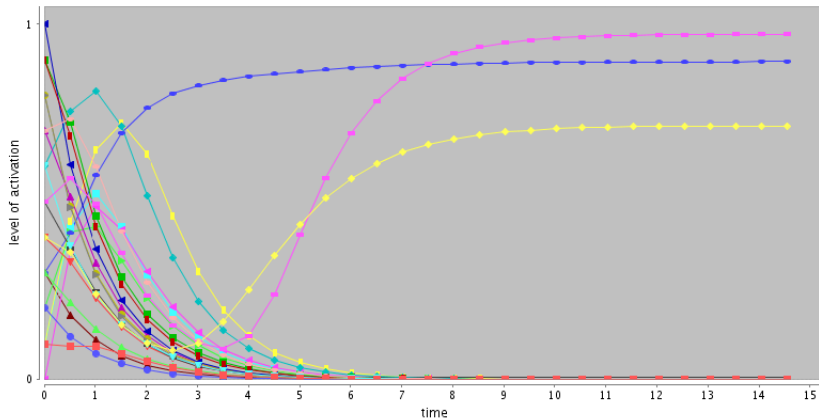
$$x \leftarrow (a \text{ AND NOT } b) \text{ OR } (\text{NOT } a \text{ AND } b)$$

$$x \leftarrow \max(\min(a, 1 - b), \min(1 - a, b))$$

$$\frac{dx_i}{dt} = \frac{-e^{0.5h_i} + e^{-h_i(\max(\min(a, 1-b), \min(1-a, b)) - 0.5)}}{(1 - e^{0.5h_i})(1 + e^{-h_i(\max(\min(a, 1-b), \min(1-a, b)) - 0.5)})} - \gamma_i x_i$$

# Finding attractors

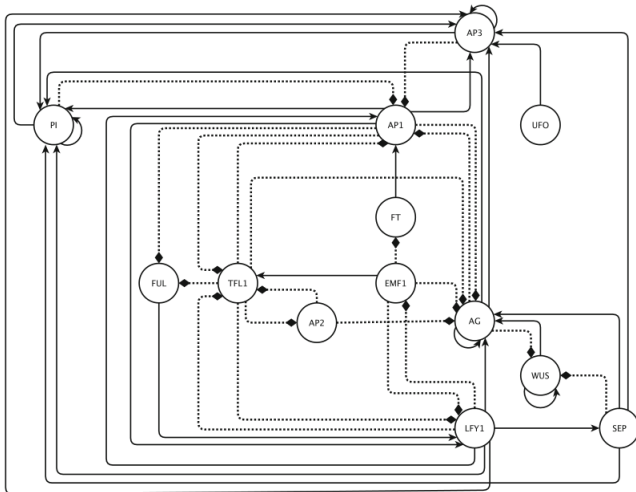
Time series



■ GATA3 ■ IFN-b ▲ IFN-bR ◆ IFN-g ■ IFN-gR ◆ IL-10 ■ IL-10R ■ IL-12 ■ IL-12R ■ IL-18 ■ IL-18R ◆ IL-4 ■ IL-4R  
◆ IRAK ■ JAK1 ■ NFAT ■ SOCS1 ■ STAT1 ■ STAT3 ■ STAT4 ■ STAT6 ■ T-bet ■ TCR

# Using SQUAD in Arabidopsis

Sánchez-Corrales *et al.* (2010). *J. Theor. Biol.* **264**: 971



# Attractors of the discrete model

	INF1	INF2	INF3	INF4	SEP	PET1	PET2	STM1	STM2	CAR
<b>AG</b>	0	0	0	0	0	0	0	1	1	1
<b>AP1</b>	0	0	0	0	1	1	1	0	0	0
<b>AP2</b>	0	0	0	0	1	1	1	1	1	1
<b>AP3</b>	0	0	0	0	0	1	1	1	1	0
<b>EMF1</b>	1	1	1	1	0	0	0	0	0	0
<b>FT</b>	0	0	0	0	1	1	1	1	1	1
<b>FUL</b>	0	0	0	0	0	0	0	1	1	1
<b>LFY</b>	0	0	0	0	1	1	1	1	1	1
<b>PI</b>	0	0	0	0	0	1	1	1	1	1
<b>SEP</b>	0	0	0	0	1	1	1	1	1	1
<b>TFL1</b>	1	1	1	1	0	0	0	0	0	0
<b>UFO</b>	0	1	0	1	0	1	0	1	0	0
<b>WUS</b>	0	0	1	1	0	0	0	0	0	0



# Attractors of the continuous model (part 1)

	INF1	INF2	INF3	INF4	SEP	PET1	PET2	STM1	STM2	CAR
<b>AG</b>	1.3E-9	1.3E-9	1.2E-9	1.2E-9	1.1E-9	1.1E-9	9.6E-10	1.0E+0	1.0E+0	1.0E+0
<b>AP1</b>	1.0E-9	1.0E-9	1.1E-9	1.1E-9	1.0E+0	1.0E+0	1.0E+0	3.1E-9	2.0E-9	3.4E-9
<b>AP2</b>	1.2E-9	1.2E-9	1.2E-9	1.2E-9	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0
<b>AP3</b>	1.2E-9	1.3E-9	1.1E-9	1.2E-9	9.5E-10	1.0E+0	1.0E+0	1.0E+0	1.0E+0	8.6E-10
<b>EMF1</b>	1.0E+0	1.0E+0	1.0E+0	1.0E+0	2.1E-9	2.0E-9	1.5E-9	1.3E-9	9.9E-10	1.4E-9
<b>FT</b>	1.1E-9	1.1E-9	1.1E-9	1.1E-9	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0
<b>FUL</b>	1.2E-9	1.2E-9	1.2E-9	1.2E-9	1.81E-9	1.8E-9	1.5E-9	1.0E+0	1.0E+0	1.0E+0
<b>LFY</b>	8.6E-10	8.7E-10	8.4E-10	8.3E-10	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0
<b>PI</b>	1.2E-9	1.2E-9	1.2E-9	1.2E-9	1.3E-9	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0
<b>SEP</b>	1.2E-9	1.2E-9	1.1E-9	1.0E-9	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0	1.0E+0
<b>TFL1</b>	1.0E+0	1.0E+0	1.0E+0	1.0E+0	9.4E-10	9.2E-10	7.8E-10	1.0E-9	1.0E-9	1.1E-9
<b>UFO</b>	5.4E-10	1.0E+0	5.2E-10	1.0E+0	5.2E-10	1.0E+0	5.2E-10	1.0E+0	5.3E-10	5.2E-10
<b>WUS</b>	5.8E-10	5.9E-10	1.0E+0	1.0E+0	5.5E-10	5.5E-10	5.5E-10	3.5E-9	2.2E-9	3.9E-9

<sup>a</sup> Values are averages of 50,000 runs (see Section 4). In all cases the associated standard deviations are smaller than 1.00E-9.

## Attractors of the continuous model (part 2)

	NEW1	NEW2	NEW3	NEW4	NEW5	NEW6	NEW7	NEW8	NEW9	NEW10	NEW11	NEW12	NEW13	NEW14
<b>AG</b>	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	1	0
<b>AP1</b>	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0	1
<b>AP2</b>	0.5	0.5	0.5	0.5	1	0.5	1	1	0.5	1	1	1	1	1
<b>AP3</b>	0	0.5	0	0.5	0	0.5	1	0	0.5	1	0.5	0.5	0.5	0.5
<b>EMF1</b>	0.5	0.5	0.5	0.5	0	0.5	0	0	0.5	0	0	0	0	0
<b>FT</b>	0.5	0.5	0.5	0.5	1	0.5	1	1	0.5	1	1	1	1	1
<b>FUL</b>	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	1	0
<b>LFY</b>	0.5	0.5	0.5	0.5	1	0.5	1	1	0.5	1	1	1	1	1
<b>PI</b>	0.5	0.5	0.5	0.5	0.5	0.5	1	0.5	0.5	1	0.5	0.5	1	0.5
<b>SEP</b>	0.5	0.5	0.5	0.5	1	0.5	1	1	0.5	1	1	1	1	1
<b>TFL1</b>	0.5	0.5	0.5	0.5	0	0.5	0	0	0.5	0	0	0	0	0
<b>UFO</b>	0	1	0	1	0	0	1	0	0	1	0	0	0	0
<b>WUS</b>	0	0	1	0.5	0	0	0	0.5	0.5	0.5	0	0.5	0	0



# Conclusion

## SQUAD:

- ▶ It is a flexible modeling tool.
- ▶ It has been extensively tested in systems with fixed point attractors.
- ▶ It still needs to be fine-tuned to study cyclic attractors.

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