

GINsim, current status and future developments

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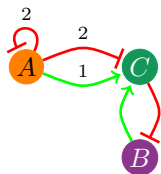


- modelling framework supported by GINsim
- GINsim main features currently available
- Next release
- Future developments: SAT and abstraction techniques

Logical formalism as supported by GINsim

Logical Regulatory Graph

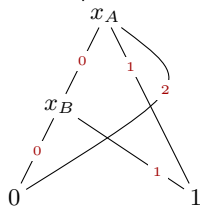
$$\mathcal{R} = (\mathcal{G}, \mathcal{I}, \mathcal{K})$$



\mathcal{K}_C : C is activated by A (at its medium level) or by B, or by both

x_a	x_b	x_c
0	0	0
0	1	1
1	0	1
1	1	1
2	0	0
2	1	0

OMDD representation

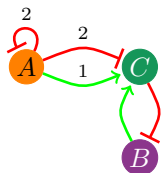


- Nodes : components (genes, proteins, ...), $i \in \mathcal{G}$, $x_i \in \{0, \dots, \max_i\}$
- Edges : interactions (activations/inhibitions), $\mathcal{I} \subset \mathcal{G} \times \mathcal{G}$, interaction (i, j) is *effective* iff $x_i \geq \theta_{i,j}$
- (Logical) regulatory function defining the component evolution

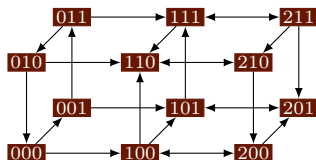
$$\mathcal{K}_i : \prod_{j \in \mathcal{G}} \{0, \dots, \max_j\} \rightarrow \{0, \dots, \max_i\}$$

Logical formalism as supported by GINsim

Logical Regulatory Graph
 $\mathcal{R} = (\mathcal{G}, \mathcal{I}, \mathcal{K})$



State Transition Graph (STG) $\mathcal{E} = (\mathcal{S}, \mathcal{T})$



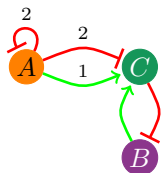
- Nodes : states $x \in \mathcal{S} = \prod_{j \in \mathcal{G}} \{0 \dots \max_j\}$
- Edges : transitions $(x, y) \in \mathcal{T}$ iff

(asynchronous)
$$\begin{cases} \exists i \in \mathcal{G} \text{ s.t. } \mathcal{K}_i(x) \neq x_i, & y_i = x_i + \frac{|\mathcal{K}_i(x) - x_i|}{\mathcal{K}_i(x) - x_i} \\ \forall j \neq i & y_j = x_j \end{cases}$$

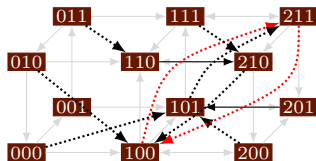
As many successors as the number of components updating their values

Logical formalism as supported by GINsim

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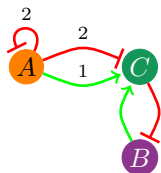
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(synchronous)
$$\begin{cases} \forall i \in \mathcal{G} \text{ s.t. } \mathcal{K}_i(x) \neq x_i, & y_i = x_i + \frac{|\mathcal{K}_i(x) - x_i|}{\mathcal{K}_i(x) - x_i} \\ \forall j \in \mathcal{G} \text{ s.t. } \mathcal{K}_j(x) = x_j, & y_j = x_j \end{cases}$$

At most one successor

Logical formalism as supported by GINsim

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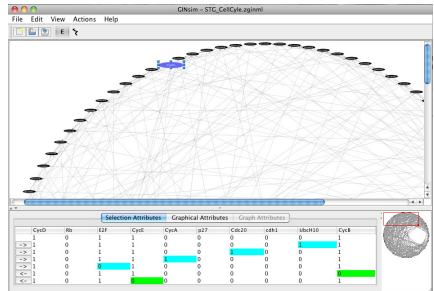
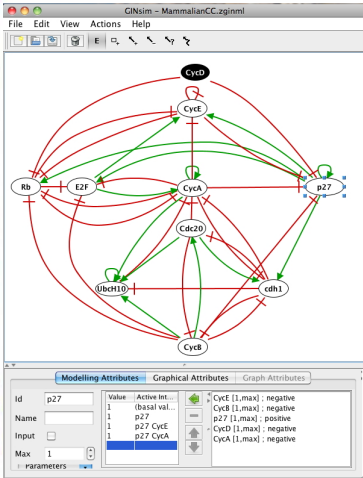
State Transition Graph (STG) $\mathcal{E} = (\mathcal{S}, \mathcal{T})$
with priority classes:

1. class C_i associated with a rank $r(C_i)$ and with an updating policy (synchronous or asynchronous);
2. several classes may have the same rank: concurrent transitions from distinct classes with identical rank triggered asynchronously;
3. at state s , trigger transitions involving components of the classes with the highest rank;
4. concurrent transitions of a class triggered accordingly to the policy associated to that class;
5. increasing and decreasing transitions can be distinguished and associated to different classes

GINsim

A dedicated tool for the qualitative modelling and analysis of regulatory networks

A. Naldi *et al* (2009) *Biosystems* 97(2):134-9, 2009



- From the model
 - Regulatory circuit analysis
 - Stable states determination
 - Model reduction
 - Mutant specification
 - Export facilities: Petri nets, Documentation
- From the dynamics
 - Construction of STG under synchronous, asynchronous and mixed priority classes
 - SCC graph
- Other export facilities: Graphviz (.dot), BioLayout, Cytoscape, SVG, PNG

- From the model
 - Import facilities: SBML qual, truth table (synchronous dynamics)
 - Export facilities: SBML qual, GNA, NuSVM, SAT
- From the dynamics
 - Hierarchical Transition Graphs: compact view of the dynamics
(→ D. Thieffry's talk)

Role and analysis of regulatory circuits

Thomas R (1988). Springer Series in Synergics 9: 180-93.

Regulatory circuits play a fundamental role in the dynamics:

- A **positive circuit** is necessary for **multistability**
- A **negative circuit** is necessary for **stable oscillations**

Role and analysis of regulatory circuits

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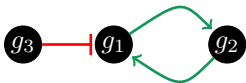
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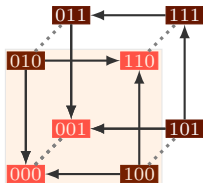
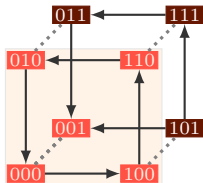
Conditions ensuring that a circuit is functional?



negative circuit functional when $x_3 = 0$



positive circuit functional when $x_3 = 0$



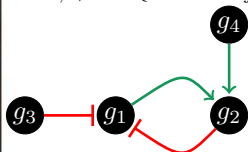
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Functionality context of $\mathcal{C} = [g_1, \dots, g_n]$: $X_{\mathcal{C}} = \bigcap_{i=1 \dots n} X_{i, i+1}$ with $X_{i, i+1} = \{s \in \mathcal{S}, \mathcal{K}_j(s) \neq \mathcal{K}_j(\bar{s}^i)\}$ functionality context of $(i, i+1)$



- $g_1 \rightarrow g_2$: $\mathcal{X}_{1,2} = \{s \in \mathcal{S}, s_3 = 0\}$
- $g_2 \rightarrow g_1$: $\mathcal{X}_{2,1} = \{s \in \mathcal{S}, s_4 = 1\}$
- $\mathcal{C} = [g_1, g_2]$: $X_{\mathcal{C}} = \{s \in \mathcal{S}, s_3 = 0, s_4 = 1\}$

A. Naldi et al. (2007) LNCS/LNBI 4695:233-247

An efficient algorithm, based on OMMDs manipulations, to determine the functionality context of regulatory circuits

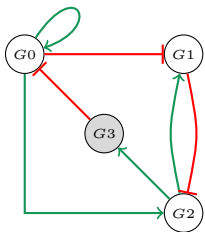
Model reduction

Reducing the STG, yet controlling the impact on its properties

A. Naldi *et al* (2011) *Theor Comp Sc* 412(21):2207-18

Define a *complete* model and reduce it by iteratively masking components (non auto-regulated)

G_3 selected for reduction



$$K_{G_0}(\mathbf{x}) = (\mathbf{x}_{G_1} = 1) \vee (\mathbf{x}_{G_3} = 0)$$

$$K_{G_1}(x) = (x_{G_2} = 1)$$

$$K_{G_2}(x) = (x_{G_0} = 1) \wedge (x_{G_1} = 0)$$

$$K_{G_3}(x) = (x_{G_2} = 1)$$

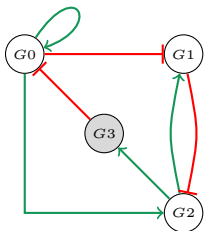
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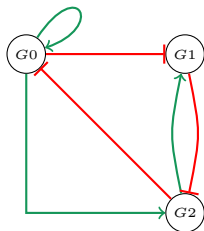
$$K_{G_0}(\mathbf{x}) = (x_{G_1} = 1) \vee (x_{G_3} = 0)$$

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$$K_{G_3}(\mathbf{x}) = (x_{G_2} = 1)$$

G_0 function revised



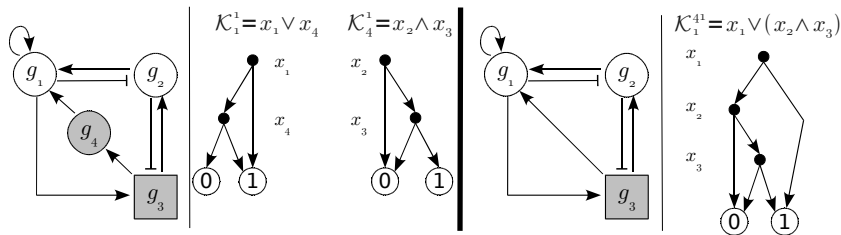
$$K_{G_0}^{G_3}(\mathbf{x}) = (x_{G_2} = 0) \vee (x_{G_1} = 1)$$

Model reduction

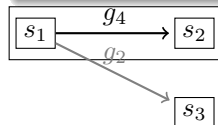
Reducing the STG, yet controlling the impact on its properties

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Computing the MDD representing \mathcal{K}_i^r from those of the original model



Reduction amounts to consider that the component is faster



Model reduction

Reducing the STG, yet controlling the impact on its properties

A. Naldi *et al* (2011) *Theor Comp Sc* 412(21):2207-18

Impact of the reduction on dynamical properties

- Terminal SCC in the STG (*i.e.* attractors) are conserved:
 - exactly the same **stable states**
 - the **elementary cycles** are conserved, new ones might appear
 - the **complex attractors** might be split, new ones might appear
- Loss of trajectories
- New (non-trivial) attractors proceed from SCCs of the original STG

Reachability in reduced STG **implies** reachability in original STG

Model-checking to investigate logical models

P. Monteiro et al (2012) PACCC'12, Adv Intel and Soft Comp, Vol. 154

- Symbolic encoding of LRG (using SMV)
- Support for different updating policies
- Reduction of the state space, considering free input variations
- Implementation in the form of an export facility in GINsim
- Property specifications encoded in CTL

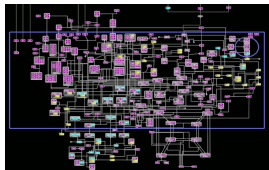
Compositional modelling framework

To tackle realistic processes, a **compositional modelling framework** is required

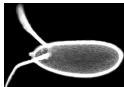
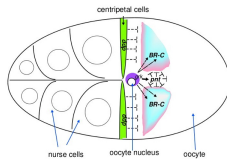
The goal is to deduce properties of the whole from the properties of the constitutive modules

Network modularity still needs to be properly identified. Multi-cellular processes provide relevant/meaningful modules

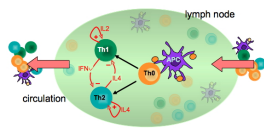
Control of proliferation



Drosophila oogenesis



T cells differentiation



Take advantage of the intrinsic **modularity** of inter-cellular regulatory networks

Compositional modelling framework

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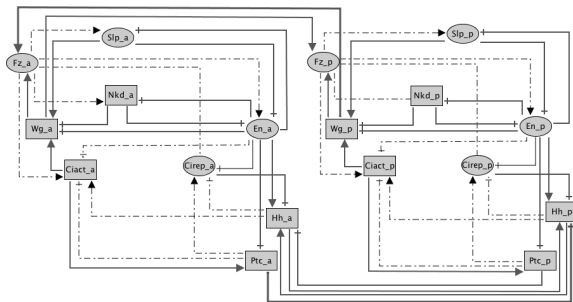
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Network modularity still needs to be properly identified. Multi-cellular processes provide relevant/meaningful modules

- *Open logical module*, with proper and input components
- *Integration function*, to convey input behaviours
- Processes specified in LOTOS NT
- Synchronisation rules
- Hidden components $\rightarrow \tau$ transitions
- Reductions (branching equivalence, partial orders)
- Check e.g. stable states reachability

Use of CADP, collaboration with VASY, INRIA Grenoble

Compositional modelling framework



	STG (GINsim)	LTS (CADP)
time	—	760 sec
size (states)	2,599,749	77
memory pic	—	1,627,348 KB

Composition of two LRMs encompassing the segment-polarity module, accounting for two cells flanking the segmental border.

Each module contains 9 components, 4 Boolean (oval nodes) and 5 ternary (rectangle nodes).

Only Wg and En are kept visible, use of safety equivalence: \rightarrow elimination of all τ transitions and preservation of stable state reachability.

(paper submitted)

Conclusions

Formal methods to handle larger models:

- SAT to assess attractors (stable states and complex cyclic attractors)
- Model-checking approaches to assess attractor reachability, properties along trajectories
- Model revision: use of the counter-examples, notion of minimal revision

Ever more important to exchange models and methods

- SBML qual
- CoLoMoTo initiative

Acknowledgements

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N. Mendes (IGC)



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